

Technical Aspects of SESAME

Maher Attal (Technical Director of SESAME) On Behalf of SESAME Technical Sector

SESAME is the only synchrotron light source in the region

There are more than 50 synchrotron light sources in the world, however SESAME is only one in the Middle East and the region.

SESAME as a synchrotron light source

SESAME as a synchrotron light sou
• SESAME produces a **synchrotron light (radiation)**:
A very intense light emitted by free electrons moving A very intense light emitted by free electrons moving at high speed (close to speed of light) whenever their trajectory is deflected.

scientific research.

SESAME from Technical Point of View

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SESAME is an electron accelerator

To produce synchrotron light, SESAME machine (Accelerators) do the following:

- SESAME is an electron accel

Fo produce synchrotron light, SESAME machine (Acce

 Extract electrons from the source (LaB6 crystal)

(Using ~ 4µs voltage pulse) SESAME is an electron accordation of the SESAME matchine (Admontration of the source (LaB6 crystal)
(Using ~ 4µs voltage pulse)
- SESAME is an electron accelerator

To produce synchrotron light, SESAME machine (Accelerators)

 Extract electrons from the source (LaB6 crystal)

 (Using ~ 4µs voltage pulse)

 Increases the electrons' speed to an **ult** using Radio Frequency (RF) system. (the microwave electric component is used to accelerate electrons)
- Deflects trajectory of the relativistic electrons (central acceleration) using magnetic field.

Other systems required to do the job

- Vacuum system: reduces the gas molecules in the way of the rotating e-beam which offers it more stability and longer lifetime.
- Control system: provides safe, synchronized, and controlled machine operation.
- Diagnostics system: characterizes the different parameters of e-beam like position, size, shape, and current value.
- Power supplies system: feeds the magnetic system with highly stable electrical power
- Cooling system: absorbs the power load on the vacuum chamber components, magnets, …

Layout of SESAME machine

SESAME machine is composed of:

- 800MeV Injector
	- Microtron
	- Booster
	- Microtron-Booster transfer line (TL1)
- \triangleright Booster-Ring transfer line (TL2)
- **► 2.5GeV storage Ring**

The 800MeV SESAME Injector

The 800MeV SESAM

SSAME

Originally from BESSY I machine. It composes:

• 20 MeV classical Microtron

- Electrons emitted and accelerated to 20MeV

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- The 800MeV S

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20 MeV classical Microtron

 Electrons emitted and accelerated to 20MeV

 RF source is Magnetron (f = 3GHz)

 Magnetic flux = 0.112 T

 Accelerated electrons are The 800MeV S

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20 MeV classical Microtron

- Electrons emitted and accelerated to 20MeV

- RF source is Magnetron (f = 3GHz)

- Magnetic flux = 0.112 T

- Accelerated electrons are s through TL1.
- 800 MeV Booster synchrotron
	-
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20 MeV classical Microtron

 Electrons emitted and accelerated to 20MeV

 RF source is Magnetron (f = 3GHz)

 Magnetic flux = 0.112 T

 Accelerated electrons are sent to Booste 3 quadrupoles each)
	-
- 20 MeV classical Microtron

 Electrons emitted and accelerated to 20MeV

 RF source is Magnetron (f = 3GHz)

 Magnetic flux = 0.112 T

 Accelerated electrons are sent to Booster

through TL1.

800 MeV Booster synchrotr them to storage ring through TL2.

Upgrades on the Injector

• All critical parts of the Microtron system are upgraded to new and modern ones

The control rack replaced with a new PLC-based one

The auxiliary gun power supply replaced with a new one designed in-house

The controller is completely SESAME design

The Thyratron-based Modulator replaced with two new SSMs (donated by INFN & PSI)

• Booster injection septum is more stabilized and Microtron & TL1 old power supplies replaced with new ones

Booster injection septum is refurbished and brought to higher level of stability

As a result,

- Microtron system is at higher level of reliability and performance
- Higher average current in the booster
- Faster filling of the storage ring

All power supplies of Microtron and TL1 replaced with new and modern ones

The 2.5 GeV Storage Ring

• Storage ring magnetic structure is compact offering 16 cells & 16 straight sections in a 133.2m
circumference.
(Bending magnets are combined-function ones & all correctors are included in the sextupole magnets) circumference. The 2.5 GeV Storage Ring

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(*Bending magnets are combined-function ones & all correctors are included in the sextup* • Storage ring magnetic structure is compact offering 16 cells & 16 straight sections in a 133.2m circumference.

(Bending magnets are combined-function ones & all correctors are included in the sextupole magnets)

• The m

26nm.rad in such short circumference.

SESAME member countries joined construction of storage ring magnets

- example in the member countries is sined construction of storage ring magnets
• Storage ring magnets are constructed through CESSAMag project in the frame of
• Bending magnets: SESAME-CERN/EU collaboration. SESAME member countries joined
• Storage ring magnets are constructed throug
SESAME-CERN/EU collaboration.
• Bending magnets:
• o constructed by TESLA (UK)
• o magnetically measured at ALBA light sou SESAME member countries joined
• Storage ring magnets are constructed throug
SESAME-CERN/EU collaboration.
• Bending magnets:
• Constructed by TESLA (UK)
• Quadrupole magnets:
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• Constructed by Elytt (SESAME member countries joined construction of storage ring
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Rending magnets:
Constructed by TESLA (UK)
one magnetic • Storage ring magnets are constructed through CESSAN

SESAME-CERN/EU collaboration.

• Bending magnets:

• o constructed by TESLA (UK)

• O magnetically measured at ALBA light source (Spain

• Quadrupole magnets:

• o the
- - o constructed by TESLA (UK)
	- o magnetically measured at ALBA light source (Spain).
- -
	- o their coils constructed by STS (Turkiye)
	- o tested and magnetically measured at CERN.
- - o their bodies constructed by CNE (Cyprus) & HMC-3 (Pakistan) (equally shared).
	- o their coils constructed by SEF (France)
	- o tested and magnetically measured at CERN

SESAME member countries joining construction of beamlines

SESAME beamlines

- Three operational beamlines:
	- o XAFS/XRF beamline: A bending magnet source
	- o IR beamline: A bending magnet source
	- o MS/XPD beamline: A 1.38T wiggler source
- Three beamlines under commissioning/ construction:
	- o HESEB (Soft X-ray) beamline: APPLE II undulator source
	- o TXPES (Soft X-ray) beamline: shares the first part of HESEB beamline.
	- o BEATS (Tomography beamline): A 3T 3PW source

SESAME member countries joining construction of beamlines

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• TXPES beamline: in collaboration with many Turkish institutions

$\frac{2}{\epsilon}$ **EEATS (BEA**mline for Tomography at SESAME) beamline
- Funded by the <u>EU's H2020</u> framework program under grant agreement n°822535
- The project is done in collaboration among many facilities: BEATS (BEAmline for Tomography at SESAME) beamline

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Photon sources at SESAME

The bending magnet (B = 1.455T, G = -2.8 T/m)

- The basic photon source in the storage ring
-
- with critical energy = 6keV.
- Electron beam size (@6.5deg) $\sigma_{\rm x}$ / $\sigma_{\rm y}$ = 232 / 81 μ m

- Photon source of material science powder diffraction beamline.
- It is composed of 33 periods of 60.5mm length and delivers a hard X-ray photon beam
- Electron beam size at middle of wiggler σ_x/σ_y = 826 / 21 µm

Photon sources at SESAME

APPLE II-type undulator ($B = 1T$ @min gap = 13.4mm & zero shift)

- Photon source of HESEB & TXPES beamlines.
- It has different operation modes (horizontal, circular, and vertical) delivering a soft X-ray photon beam of a tunable polarization
- Electron beam size at middle of undulator σ_x/σ_y = 826 / 21 µm

New: commissioned in June, 2022

Three-pole wiggler ($B = 3T$ @min gap of 11.15mm)

- Photon source of BEATS beamline
- Delivers a single source hard X-ray photon beam
- Electron beam size at middle of wiggler σ_x/σ_y = 821 / 14 µm

New: commissioned in September, 2022

First Accelerator in the World Powered by Renewable Energy

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SESAME Vacuum System

By Abid Ur Rehman, Vacuum group

Vacuum Pumps

Turbomolecular Pumps

Pressure Range: 10⁻³ to 10⁻¹⁰ mbar

Ion Pumps

High Vacuum Ultra High Vacuum

Pressure Range: 10^{-7} to <10⁻¹⁰ mbar

Vacuum Valves/ Components

SESAME

Vacuum Gauges & Controllers

High/Ultra High
Vacuum Gauges Full Range Gauges (10-3 to 10-11 mbar)

Vacuum Gauges Full Range Gauge
 $(10^{-3}$ to 10^{-11} mbar) (atm. to 10^{-9} mbar)

Gauge Controllers

Ion Pump Controllers

Vacuum Leak Detection & RGA

Helium Leak detector

Helium Leak Detector

Residual Gas Analyzer (RGA)

SESAME Control System

By A. Abbadi, Control group

• SESAME control system utilizes Experimental Physics and Industrial Control System (EPICS)
toolkit for both Machine and Beamlines. SESAME control system utilizes Experimental Physics and Industrial Condiction Machine and Beamlines.

EPICS-based control system has basic components:

- **IOC** (Input/Output Controller): serves as the I/O server,
and acts as a middle layer between various devices
(instruments, sensors, detectors, ..) and other EPICS tools
and clients (GUI, Python script, MATLAB script, ..)

- applications.
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Reference: https://docs.epics-controls.org/

- Control system allows: access, monitor and control over the different devices from computers
(workstations) located in the accelerators' control room and beamlines' control hutches.
• The role of control system can be su
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Timing System

It generates and distributes hardware trigger signals and synchronization clocks around the accelerator facility

System structure:

- VME Based Event Generator/Receiver System.
- Signal distribution via fiber-optic links.
- 500 MHz reference clock (Master Oscillator).

Features and Functions:

- Provides highly stable reference (clocks).
- Synchronization of different subsystems.
- Controls Beam Injection and Extraction.

Safety system - Machine Protection System
tion System (MPS) is implemented using SIEMENS S7-300 PLCs

Machine Protection System (MPS) is implemented using SIEMENS S7-300 PLCs

It protects machine components from abnormal conditions: • Low water flow
• Low water flow
• High temperature
• High gas pressure (or bad vacuum)
• Large deviation in e-beam position (> ± 1mm)
• Protects insertion devices against hazardous motion
• Controls the photon shutters i

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Safety system - Personnel Safety System

nnel evacuation procedure from

ion area before accelerator operation

SESAME PSS Functions
Protect people from entering the

Personnel evacuation procedure from **EDD** BO Main SR Main BO Procedures SR Procedures radiation area before accelerator operation

Human Machine Interface (HMI) provides real-time information on various aspects buttons, tunnel status, personal keys status, doors status)

SESAME Diagnostics System

By H. Al-Mohammad, Diagnostics group

Florescent / Scintillator Screens

- Fixed on Pneumatic and stepper motor actuators
- Screens used: Al2O3, CdWO4 (Cadmium Tungstate), YAG:Ce, Phosphor screens P43, PreLude
- The cameras used:
	-
- Florescent / Scintill
Fixed on Pneumatic and stepper motor actuators
Screens used: Al2O3, CdWO4 (Cadmium Tungstate), YAG:Ce,
Phosphor screens P43, PreLude
The cameras used:
- CCD (Charged Coupled Device) camera
- CMOS (Com triggered camera (1/3" sensor 3.75x3.75um pixel size)

Beam Profile Measurement

SESAME

• Visible light method: by dirt imaging and interferometry method. \blacksquare

Photon beam extracted using in-vacuum mirror.

• Measured vertical beam size \sim 84 μ m (theoretical value \sim 81 μ)

Beam Profile Measurement

• X-ray method: using a pinhole camera with very small hole sizes $\begin{aligned} \textbf{Beam Problem} \textbf{1} \end{aligned}$
 $\begin{aligned} \textbf{10*10}\ \textit{\textbf{M}}\textbf{=} \end{aligned} \begin{aligned} \textbf{10*10}\ \textit$

- The pinhole assembly controlled by 5 degree transition stage with micro-stepping motor.
- The measured vertical beam size \sim 76 μ m.

Beam Position Measurement

- **EXECT BEAM POSITION MEASUREMENT**

 Done using beam position monitor (BPM) connected to advanced electronics, Libera Brilliance+, based on

 Different types of data obtained: Raw ADC acquisition, turn-by-turn

 Differen
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- with phase matching.
- Extremely low temperature drift (RMS): 0.2 μm/C for slow data, 0.5μm/C for turn-by-turn, and 0.07μm/C for FA.

Beam Position Measurement

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Hardware Fast Orbit Interlock Built in-House

- A simple, robust and low cost hardware Fast Orbit Interlock Built in-House

 A simple, robust and low cost hardware Fast Interlock system and Post Mortem

 Used to protects the machine from e-beam. Mardware Fast Orbit Interlock Built in-House.

• A simple, robust and low cost hardware Fast Interlock system and Post Mortem

• Used to protects the machine from e-beam.

• It acts very fast:

• Othe system latency < 22µs Hardware Fast Orbit Interlo
• A simple, robust and low cost hardware Fast Interlock sy
designed and assembled in-house.
• Used to protects the machine from e-beam.
• It acts very fast:
• o the system latency < 22µs
• o the Hardware Fast Orbit Interlock Built in
A simple, robust and low cost hardware Fast Interlock system and Pos
designed and assembled in-house.
Jsed to protects the machine from e-beam.
t acts very fast:
o the system latency
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Beam stability at SESAME

- The e-beam orbit is stabilized using only a Slow Orbit Feedback system (orbit correction rate 0.2Hz).
- Sufficient beam stability achieved **EGALLA** SRCO2-IDOS-BPMOI- Show X&Y- $<$ 4 μ m (i.e. $<$ 5% of beam size) serves arcoz-idos-aprool (id s)
- The work on Fast Orbit Feedback system is ongoing (orbit correction rate > 50 Hz)

Libera 8

Corrector PS

Controllers

32 PS for each plane for 64 corrector magnet

Beam Loss Detection

- Four Beam Loss Detectors (BLD) installed in the machine and connected to one Beam Loss Monitor (BLM).
- The detectors from I-Tech, EJ-200 with Hamamatsu 10721-110 PMT , are very fast and sensitive
- Very useful in machine studies (extraction, transmission, injection, ID commissioning, …etc)

Beam Current Measurement

- Done using Fast Current Transformers (FCT) and DC Current Transformers (DCCT) from Bergoz, with radiation
• FCT has high sensitivity 2.5V/A, with 1.7GHz cutoff frequency, connected to 1GHz Tek scopes (20GS/s). Beam Current Measurement

• Done using Fast Current Transformers (FCT) and DC Current Transformers (DCCT) from Bergoz, with radiation

• FCT has high sensitivity 2.5V/A, with 1.7GHz cutoff frequency, connected to 1GHz Tek
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SESAME Power Supplies System

By S. Jafar, Power Supplies group

DC Power Supplies

- **DC Power Supplies**
• Required for driving DC electromagnets of the mach
• Current Regulated power supplies
• High Precision (50-100ppm)
• High Stability (100ppm/8h) **DC Power Supplies**
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• High Stability (100ppm/8h) **DC Power Supplies**
• Required for driving DC electromagnet
• Current Regulated power supplies
• High Precision (50-100ppm)
• High Stability (100ppm/8h)
• Technologies used:
-
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- - Technologies used:
		- o 12-24 pulse rectification
		- o Switched mode power supplies
		- o DCCT
		- o High precision ADC / DAC
		- o Thermal regulation
		- o Realizes EMC/ Safety standards

Pulsed Magnets' Power Supplies

- **Pulsed Magnets' Power Supplies**
• Required to drive pulsed electromagnets (Kickers and Septums) used to transfer
• High Speed (1µs-100µs) electron beam from accelerator to another Pulsed Magn
• Required to drive pulsed electromagn
• High Speed (1µs-100µs)
• High Voltage (30kV)
• High Current (5kA) Pulsed Magn
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• High Voltage (30kV)
• High Current (5kA) **Pulsed Magn**
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• electron beam from accelerator to and
• High Speed (1_{US}-100_{US})
• High Voltage (30kV)
• High Current (5kA) Pulsed Magnets' Pow

• Required to drive pulsed electromagnets (Kicker

• High Speed (1_{µs-100µs)}

• High Voltage (30kV)

• High Current (5kA)

• Technologies used in pulsed magnets:

• Technologies used in pulsed magnets
-
-
-
- - o Magnetic Design and analysis.
	- o µm Thick Titanium Coating.
	- o Precision Machining.
	- o PFL/PFN Energy Transfer.
	- o Thyratron (high power switch).
	- o High Voltage Solid State Switches.

SESAME Radio Frequency System

By D. Foudeh, RF group

SESAME RF Main Block Diagram

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Main Directional Coupler

SESAME RF SSAs

Radio Frequency Cavity

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- Elettra-type RF Cavity.
- Free oxygen copper made with elliptical shape.
- by axial compression/decompression.
- Max. input power at coupler is 110KW.

Four RF cavities in the

Cavity Cooling Rack

- Cavity Cooling Rack
• Keeps temperature of the RF cavity to a pre-defined value $(30 75)$ °C.
• Design accuracy ±0.05°C (achieved ±0.2°C).
-
- Cavity Cooling Rac
• Keeps temperature of the RF cavity to a pre-defined
• Design accuracy ±0.05°C (achieved ±0.2°C).
• Primary circuit works at 7.5bar and 5m³/h while the
secondary circuit works at 8bar and 12m^{3/}h. • Primary circuit works at 7.5bar and 5m³/h while the secondary circuit works at 8bar and 12m³/h.

Low Level Electronics
em programmed to control RF $\frac{\mathbf{x}_{\text{u}, \text{Rf}, \text{Top Pand (One Curity)QSNR: GEN-VEB-OPOI}, \text{resemalical}}}{\mathbf{x}_{\text{u}, \text{Rf}, \text{Top Pand (One Curity)QSNR: GEN-VEB-OPOI}, \text{resemalical}}}$

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Alignment System & Mechanical Engineering

By A. Hasoneh & M. Shehab, Mechanical Engineering group

- Alignment:
	- A) Rough Alignment. (in mm)
	-
- Alignment at SESA

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Alignment:

A) Rough Alignment. (in mm)

B) Accurate alignment. (in micro meter)

Mechanical inspection & Reverse Engineering. • Mechanical inspection & Reverse Engineering. E
Alignment:
A) Rough Alignment. (in mm)
B) Accurate alignment. (in micro meter)
Mechanical inspection & Reverse Engineerin
Tools and Instruments used:
o Laser Tracker 402 Leica.
o TDA 5005
o Optical LEVEL NA2 Leica. Alignment:
A) Rough Alignment. (in mm)
B) Accurate alignment. (in micro meter)
Mechanical inspection & Reverse Engineerin
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Mechanical inspection & Reverse Engineerin
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O Laser Tracker 402 Leica.
O TDA 5005
O Optical LEVEL NA2 Leica.
O Accurate water levels.
O Laser Lines. Mechanical inspection & Reverse Engineerin
Tools and Instruments used:
O Laser Tracker 402 Leica.
O TDA 5005
O Optical LEVEL NA2 Leica.
O Accurate water levels.
O Laser Lines.
- Tools and Instruments used:
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"In the realm where precision matters most, We ensure that every optical element finds its perfect place in the Synchrotron facility."

A) Rough Alignment (in mm)

$B)$ Accurate alignment (in μ m)

Multi layers filter and End stations alignment

$B)$ Accurate alignment (in μ m)

Results of chamber alignment (Maximum waviness) 0.05mm.

Using Laser Tracker Network for monitoring and

Mechanical inspection & Reverse Engineering

scanning for BEATS H-Slit

Mechanical Design Work

- Examples
	- o Static filter for MS/XPD Beamline

ME Design Support For New Beamlines

• BEATS Insertion Device chamber including up stream and down stream sections

- In Vacuum section installed & Aligned.
- Camera + Scintillator installed and aligned.

Projects - Supports of BEATS ID section vacuum pumps

 $\begin{array}{|c|c|}\n\hline\n\text{SR-GS-7607-P} \\
\hline\n\text{S136} \\
\text{G1Y: 1}\n\end{array}$ SR-GS-7606-P $4 \times 0.107980 \text{ AL}$ $\frac{159.37}{153.62}$ 4x @ 15 THRU Note:
Remove all I
Painting:
1- Primer Co
2- Epoxy pai **O x Ø 5 THRU ALL**
M6 - 6H THRU ALL : x Ø 10.20 THRU ALL
M12 - 6H THRU ALL $2x$ Ø 35 THRU 450 $\frac{1}{\text{SR-GS-7603-P(~Rigid space)}}$
SST316
QTY: 2 **ANE IN MILLINET** ight for Experimental
ations in the Middle I BEATS_ID_Flexible support_R2 Life Cycle
For Quote SR-GS-7600-A \mathbb{A}^n 6X Ø 12 TH NUESS OTHERWISE SPECIFIES light for Experimental Sci
ications in the Middle East i fry Life Cycle For Quote **SR-GS-7600-A** $A₃$ $\frac{1}{2}$ For Quote \bigoplus 115 $-2059 - 16$ SR-GS-7600-A $A3$ maps no 8048118 -

Thank you